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Main Manuscript for

The roles of cultural transmission and causal reasoning in the cultural evolution of technology

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29 **Abstract**

30 Humans are uniquely capable of producing highly efficient tools, but the extent to which this
31 capacity depends on individual reasoning abilities remains unclear. In particular, the respective
32 roles of causal and technical reasoning versus cultural transmission in driving technological
33 improvement are the subject of long-standing debate. We address this question by directly
34 manipulating causal and technical reasoning in transmission chains, where participants
35 sequentially inherit and refine prior solutions. Across two transmission chain experiments,
36 participants (n = 900) completed tasks under three conditions: (1) technical reasoning, involving
37 physical tasks and intuitive physics; (2) causal reasoning, where similar causal structures could be
38 exploited without physical context; and (3) pure cultural transmission, in which causal structures
39 were removed. We found that cumulative improvement occurred across generations even in the
40 absence of causal structure, demonstrating that cultural transmission alone can drive technological
41 improvement. While causal reasoning accelerated early improvement by helping participants focus
42 on promising regions of the design space, its impact diminished over time. Notably, technical
43 reasoning offered no added benefit over causal reasoning. These results highlight the beneficial
44 yet dispensable role of causal reasoning in the improvement of culturally evolving technology, and
45 challenge the view that improvements guided by causal models depend on domain-specific rather
46 than domain-general reasoning abilities.
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48 **Significance Statement**

49 Human adaptation to diverse habitats has been enabled by complex technologies, raising key
50 questions about the role of individual reasoning abilities in their development. This study introduces
51 a novel methodology for rigorously evaluating how causal and technical reasoning, compared to
52 cultural transmission, contribute to technological improvement. Across two experiments, we show
53 that cultural transmission alone can lead to improvement, even in the absence of causal reasoning.
54 Causal reasoning accelerates early improvement, although its influence diminishes over time.
55 Technical reasoning (i.e., reasoning grounded in intuitive physics) offers no advantage compared
56 to causal reasoning. By disentangling the roles of reasoning and cultural transmission in
57 technological evolution, these findings offer new insight into the cognitive and cultural processes
58 that have shaped the evolution of human technology.
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72 **Main Text**

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74 **Introduction**

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76 Causal reasoning is often seen as a defining feature of human cognition [1-3]. Humans effortlessly
77 think in terms of causal relationships and can easily identify “difference-making” variables, which
78 are variables that influence other variables [3]. Identifying those variables allows humans to design
79 interventions and adjust them to achieve desired outcomes. For example, when improving a basic
80 hunting tool like a spear, one may identify the sharpness of the point as a key “difference-making”
81 variable and could decide to make it sharper to increase the spear’s perforating capability.

82 The ability to exploit “difference-making” variables is sometimes presented as the key
83 factor underlying humans’ capacity to design efficient tools [4-6]. For instance, causal reasoning
84 has been argued to support tool invention and iterative improvement through feedback during an
85 individual’s lifetime [4, 6]. Related accounts have emphasized technical reasoning, defined as a
86 specific form of causal reasoning directed at understanding the physical world, as central to
87 technological improvement [5].

88 Yet, the effectiveness of causal reasoning has been challenged in the context of complex,
89 high-dimensional technologies commonly found in human populations [7-9]. In such systems, even
90 small changes to one feature can produce unforeseen consequences in others. For example,
91 adjusting a bowstring to increase arrow speed might inadvertently increase vibration, resulting in a
92 worse overall outcome. This interdependence between features creates what some researchers
93 refer to as the “complexity barrier” to artifact improvement [10] and often demands computational
94 resources beyond human cognitive capacity [7, 11].

95 These limitations suggest that alternative or complementary mechanisms may be required
96 for the emergence of highly optimized tools. One proposed mechanism is payoff-biased social
97 learning, in which individuals adopt solutions that have previously led to successful outcomes in
98 others [12-14]. When such a selective process operates across generations, it may yield highly
99 efficient solutions even when individuals lack an understanding of why those solutions work [7, 15]
100 see also [16]. In support of this, experimental work has shown that the gradual improvement of a
101 technology across generations is not necessarily accompanied by increased understanding [17].
102 Similarly, interviews with Hadza bowyers suggest that their understanding of how relevant variables
103 affect bow efficiency is limited [18].

104 Nonetheless, neither line of evidence fully dismisses the role of causal reasoning in
105 technological improvement [19]. For instance, participants in experimental studies tend to direct
106 their exploration toward specific regions of the parameter space, suggesting that causal reasoning
107 may help guide exploration toward promising regions [17, 19]. Moreover, other experiments found
108 that improvements can coincide with increased understanding [20].

109 Critically, because existing studies have focused on whether improvement across
110 generations correlates with increased understanding [17, 20], they have not allowed direct

111 assessment of the actual contribution of causal reasoning. As a result, a major gap remains in
112 understanding the role of causal reasoning in technological evolution, with significant implications
113 for inferring the cognitive and cultural processes that have shaped the evolution of human
114 technology.

115 Here, we present a novel methodology that allowed us to experimentally manipulate
116 participants' ability to rely on either causal or technical reasoning while solving a task within
117 transmission chains. This approach enabled us to test whether cultural transmission on its own can
118 lead to improvement across generations and to assess the extent to which both forms of reasoning
119 further enhance this process.

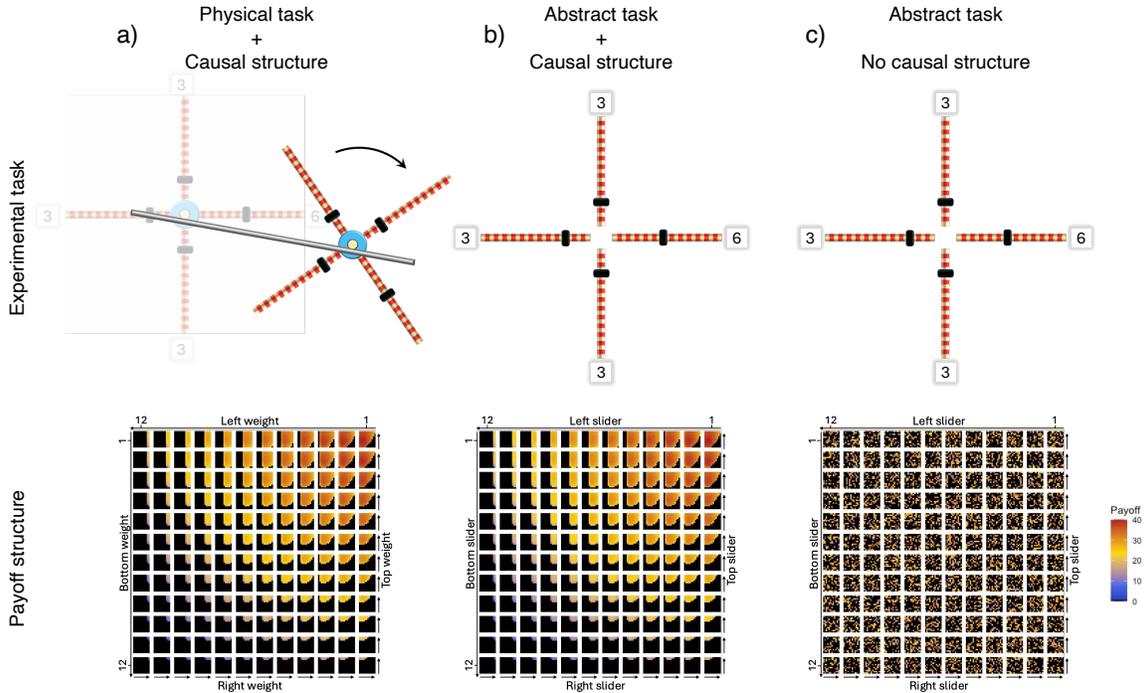
120 Our methodology builds on a physical task used in prior research [17] and uses the same
121 four adjustable parameters across three experimental conditions (Figure 1) , varying only the
122 information available to participants. These conditions were implemented in transmission chains
123 where participants sequentially inherit and refine prior solutions [21, 22].

124 In the Technical Reasoning condition, the input variables represented the four weights of
125 the wheel task from [17]. Participants adjusted weights along the radial spokes of a digital wheel to
126 select a configuration, which determined two physical properties: the wheel's moment of inertia and
127 the position of its centre of mass. These properties determined the causal structure of the task,
128 which participants could learn and exploit by observing covariation between inputs (i.e., weight
129 positions) and output (i.e., their payoff, as determined by the time it takes the wheel to travel down
130 the track). In this treatment, participants could observe the wheel's motion, potentially allowing them
131 to draw on intuitive physics to refine their causal model of how weight positions govern its
132 mechanical behaviour (Figure 1.a).

133 In the Causal Reasoning condition, participants were informed that the task involved
134 adjusting four sliders, with no physical context provided, rendering the task fully abstract (Figure
135 1.b). Participants could not observe the wheel's motion and therefore could not draw on intuitive
136 physics to refine their causal model of the task. However, the task retained the same underlying
137 payoff structure as the wheel task, enabling them to exploit identical covariation patterns between
138 input variables (i.e., slider positions) and output variables (i.e., payoffs).

139 Finally, in the Pure Cultural Transmission condition, the task was fully abstract and lacked
140 any underlying causal structure. In this treatment, slider configurations were assigned fixed payoffs
141 randomly drawn from the original payoff distribution, breaking the mapping between inputs and
142 outputs and preventing participants from exploiting causal variables (Figure 1.c). As a result, any
143 improvement observed across generations could only arise from the combined effects of random
144 exploration and cultural transmission.

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Figure 1: Experimental conditions. a) *Technical reasoning:* Participants are informed that the task involves a wheel rolling down a track. After selecting the positions of the four weights, participants observe the wheel’s motion on an inclined track and then receive a payoff, determined by the time it takes the wheel to travel down the track. The task features a stable mapping between weight positions and payoff, mediated by physical properties (moment of inertia and centre of mass), allowing participants to rely on intuitive physics. b) *Causal reasoning:* Participants are informed that the task involves adjusting four sliders, with no physical context provided. After selecting the positions of the four sliders, participants receive a payoff. Although participants cannot rely on intuitive physics, the task retains the same underlying payoff structure as the wheel task, enabling them to exploit covariation patterns between slider positions and payoffs. c) *Pure Cultural Transmission:* Participants are informed that the task involves adjusting four sliders. After selecting the positions of the four sliders, participants receive a payoff. Here, the causal structure is removed: slider configurations are assigned fixed payoffs randomly drawn from the original payoff distribution, breaking the mapping between inputs and outputs and preventing participants from exploiting causal variables. In the bottom plots, payoff is shown as a function of the positions of the top, right, bottom, and left weights/sliders (with 1 corresponding to the innermost position). The plot is organized as a grid of squares, where each square represents a unique combination of left and bottom slider values: the left slider varies across columns of the outer grid, and the bottom slider varies across its rows. Variation in the right and top sliders is shown within each square: the right slider varies across columns, and the top slider across rows. Black cells indicate configurations with a payoff of zero, corresponding to wheel configurations that fail to descend the rails upon release.

The experiment was pre-registered and structured as follows: All participants (n = 450) were randomly assigned to one of three experimental conditions and placed into transmission chains consisting of five individuals (30 chains per condition). Each participant completed five trials with the goal of maximizing their own cumulative payoff and the payoff of the next participant in the chain. Before each trial, all participants, except those in the first generation, could consult the two most recent configurations produced within their chain along with their associated payoffs.

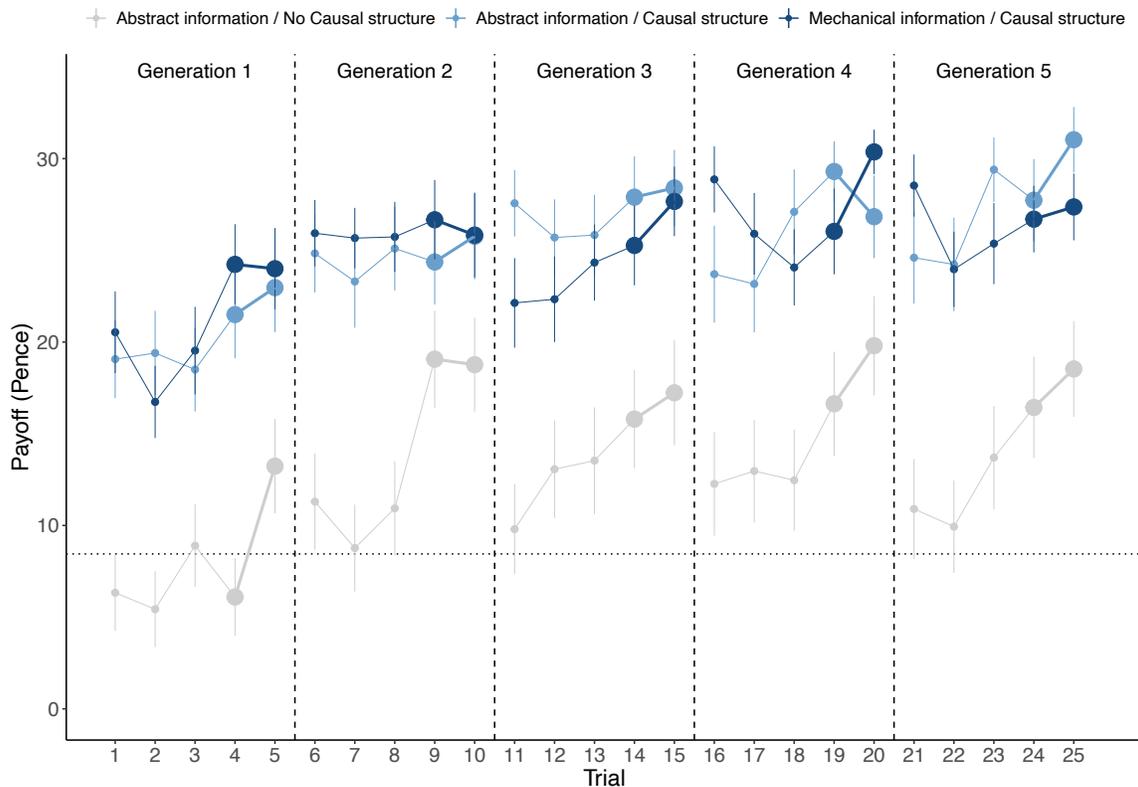
In line with the view that cultural transmission can drive technological improvement without causal reasoning, we predicted that cumulative improvement would occur across generations in all conditions, including the Pure Cultural Transmission condition. However, we expected the pace of

177 improvement to be faster in the Causal Reasoning condition. We did not make specific predictions
178 regarding the relative pace of improvement in the Technical and Causal Reasoning conditions.

179
180 **Results**

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182 The average payoff increased across generations in all conditions (Pure Cultural Transmission:
183 Generation 95% CI [0.60, 1.98], mean = 1.29; Causal Reasoning: Generation 95% CI [0.85, 2.36],
184 mean = 1.61; Technical Reasoning: Generation 95% CI [0.50, 1.95], mean = 1.23). Among
185 participants who completed an abstract version of the task, performance was higher when the
186 causal structure was present (Causal Structure 95% CI [6.93, 14.87], mean = 10.95; Causal
187 Structure x Generation 95% CI [-0.69, 1.41], mean = 0.37). Performance did not differ between
188 participants presented with the physical version of the task and those presented with the abstract
189 version when the causal structure was present (Physical Task 95% CI [-1.73, 3.85], mean = 1.05;
190 Physical Task x Generation 95% CI [-1.19, 0.44], mean = -0.39).

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193 **Figure 2.** In Experiment 1, payoff increased across generations in all conditions. Vertical dashed lines
194 separate successive generations, with large dots representing culturally transmitted trials. The horizontal
195 dotted line marks the mean of the payoff distribution. Error bars represent the standard error of the mean.

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197 Although these results align with our pre-registered prediction that participants in the
198 Causal Reasoning condition would outperform those in the Pure Cultural Transmission condition,
199 the observed statistical differences do not fully match our expectations. Specifically, we expected

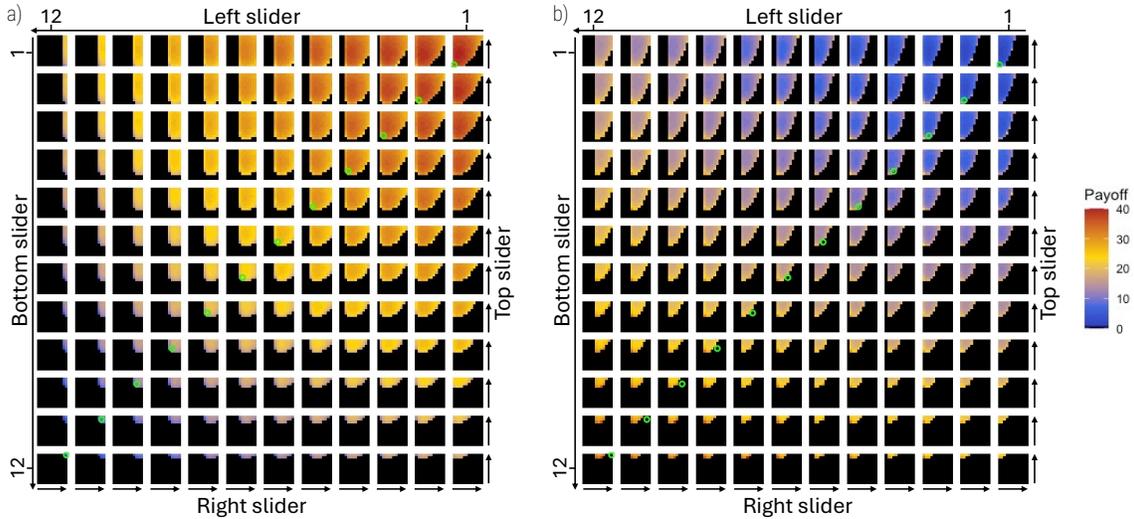
200 the Causal Structure \times Generation interaction to yield a reliably positive effect, rather than a main
201 effect of Causal Structure alone. This prediction was based on the assumption that participants
202 facing any version of the abstract task would initially be naive about what might constitute a better-
203 than-random configuration. However, our results show that first-generation participants in both the
204 Technical and Causal Reasoning conditions produce configurations with payoffs more than twice
205 the average of the distribution (Figure 2).

206 Exploratory analyses revealed that this difference stems from first-generation participants'
207 tendency to produce balanced configurations (i.e., configurations with weights/sliders positioned at
208 equal distances from the axis) during their early trials across all conditions. Balanced configurations
209 are associated with above-average payoffs in both the Technical and Causal Reasoning conditions
210 because balanced configurations always roll down the inclined rails, guaranteeing a non-zero
211 payoff with a probability of 1 and an average payoff of 22.6. In contrast, unbalanced configurations
212 do not consistently roll down, yielding a non-zero payoff with a lower probability of 0.32 and a lower
213 average payoff of 8.44. This contrasts with the Pure Cultural Transmission condition, where
214 balanced and unbalanced configurations yield similar average payoffs, as all configurations are
215 randomly assigned a payoff drawn from the wheel's payoff distribution.

216 This leaves open the possibility that our results underestimate the role of technical
217 reasoning. For instance, participants in the Technical Reasoning condition may have been more
218 likely to produce balanced configurations due to useful priors grounded in intuitive physics, while
219 those in the Causal Reasoning condition may have benefited from an irrelevant aesthetic or
220 cognitive preference for balanced patterns. Additionally, participants in the Causal Reasoning
221 condition may have outperformed those in the Pure Cultural Transmission condition due to an
222 artifactual head start, rather than an effective exploitation of the task's underlying causal structure.

223 To address these possibilities, we conducted Experiment 2, which used a modified version
224 of the task calibrated so that balanced and unbalanced configurations had similar average payoffs,
225 with the greatest potential gain coming from producing unbalanced configurations (i.e.,
226 configurations with weights/sliders positioned at unequal distances from the axis). To achieve this,
227 we recruited 450 additional participants and provided them with a wheel featuring unequal weights
228 (Supplementary Figure 1) and an inverted goal: to produce wheels that moved as slowly as possible
229 while still descending the rails. Figure 3 illustrates how these changes effectively shifted the most
230 rewarding solutions to another area of the parameter space while maintaining a causal structure
231 comparable to that of Experiment 1.

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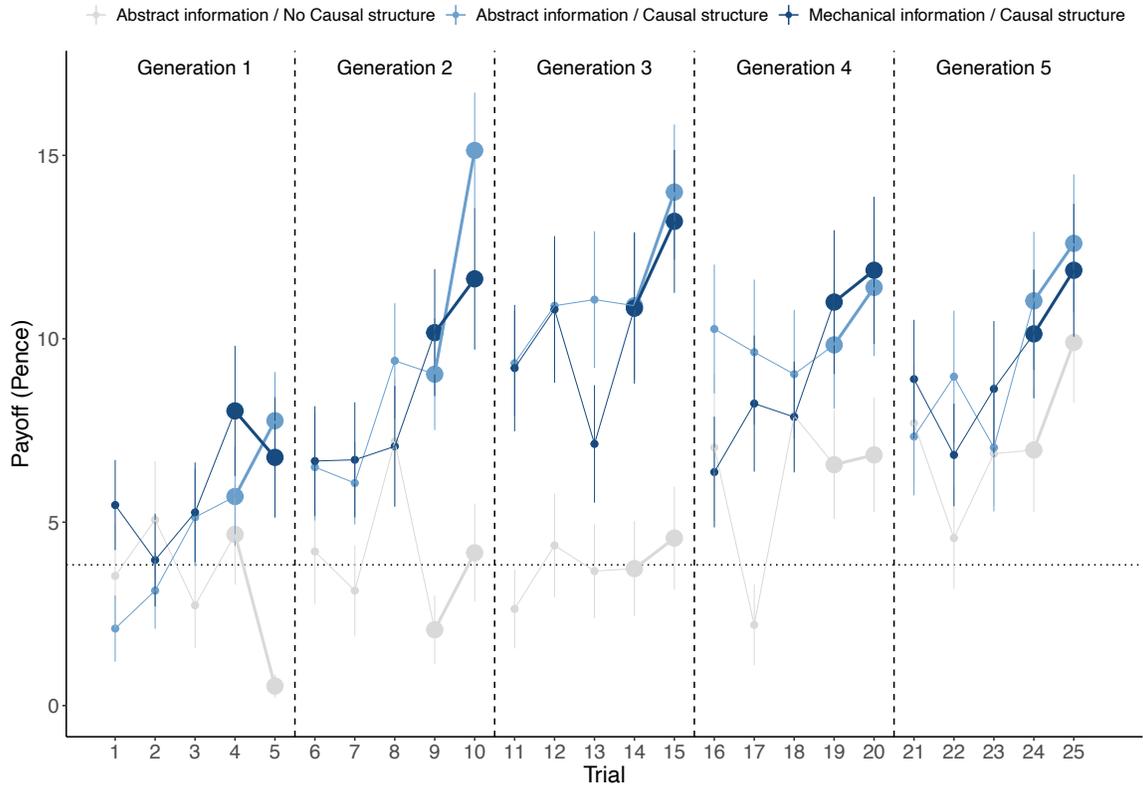


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Figure 3: Comparison of the payoff structure in Experiments 1 and 2. a) Experiment 1: The mapping between weight positions and payoff is mediated by the physical properties of a wheel featuring weights of equal mass. Since the goal is to minimize the time it takes the wheel to complete the track, the task rewards configurations with a low moment of inertia (i.e., weights positioned closer to the axis) and a centre of mass located in the upper right side of the wheel (toward the slope). Because the weights are equal, all balanced configurations (i.e., configurations with weights/sliders positioned at equal distances from the axis) roll down the rails and yield a positive payoff (lime green circles), ranging from low to high. The best configuration in this experimental treatment was: Top = 5; Right = 3; Bottom = 1; Left = 1. b) Experiment 2: The wheel features weights of unequal mass, with the right-side weight being heavier. Since the goal is to maximise the time it takes the wheel to complete the track, the task rewards configurations with a high moment of inertia (i.e., weights positioned far from the axis) and a centre of mass located on the left side of the wheel (away from the slope). Because the weights are unequal, balanced configurations do not consistently roll down the rails and may yield either zero payoff or a low positive payoff (lime green circles). The best-performing configuration in this treatment was: Top = 11; Right = 6; Bottom = 12; Left = 8. Note how in Experiment 2 the most rewarding solutions (orange/red cells) tend to cluster in riskier regions of the parameter space, where non-viable solutions (black cells) are more common.

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Results from Experiment 2 indicate that the implemented changes successfully eliminated the early above-average payoffs observed in the Causal Reasoning condition of Experiment 1. Crucially, the qualitative pattern of results remained consistent across experiments, with average payoff increasing across generations in all conditions (Pure Cultural Transmission: Generation 95% CI [0.51, 1.43], mean = 0.97; Causal Reasoning: Generation 95% CI [0.42, 1.63], mean = 1.01; Technical Reasoning: Generation 95% CI [0.13, 1.39], mean = 0.74). Among participants who faced an abstract version of the task, performance was higher when the causal structure was present rather than absent (Causal Structure 95% CI [1.83, 5.95], mean = 3.86; Causal Structure x Generation 95% CI [-0.57, 0.66], mean = 0.05). Performance did not differ between participants presented with the physical version of the task and those presented with the abstract version when the causal structure was present (Physical Task 95% CI [-1.79, 2.60], mean = 0.43; Physical Task x Generation 95% CI [-0.90, 0.37], mean = -0.26).



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 265 **Figure 4.** In Experiment 2, payoff increased across generations in all conditions. Vertical dashed lines indicate
 266 successive generations, with large dots representing culturally transmitted trials. The horizontal dotted line
 267 marks the mean of the payoff distribution. Error bars represent the standard error of the mean.
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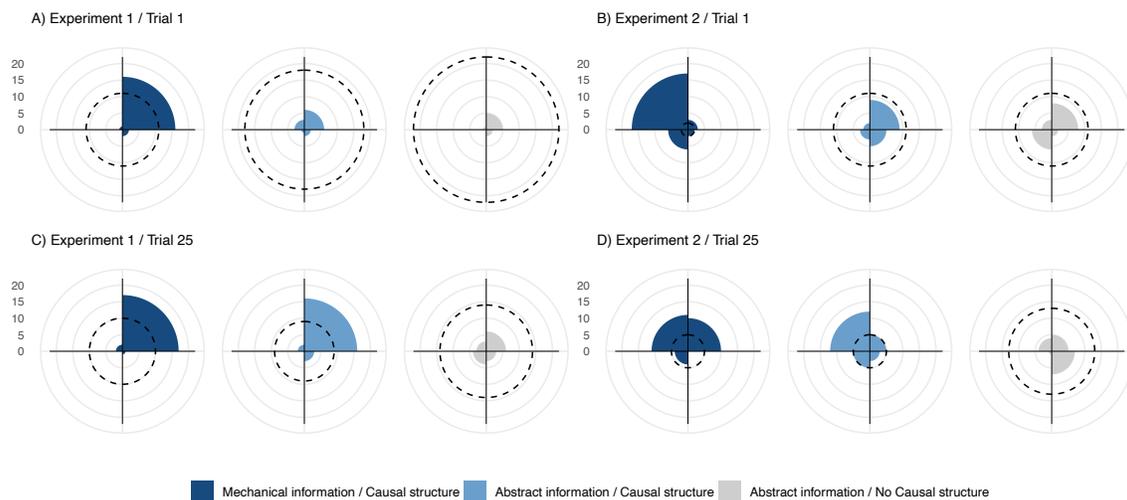
269 As shown in Figure 4, the higher performance of participants who faced a version of the
 270 task with an underlying causal structure appears to be driven primarily by the first three generations
 271 of learners, after which performance begins to plateau. Exploratory analyses indicate that this effect
 272 stems from a feature of the payoff structure of Experiment 2 where moving toward more rewarding
 273 solutions in the Technical and Causal Reasoning conditions brings learners into riskier regions of
 274 the parameter space where non-viable solutions are more common (Figure 3.b). This contrasts
 275 with the payoff structure of Experiment 1, where moving toward more rewarding solutions brings
 276 learners into safer regions of the solution space (Figure 3.a). This means that in the two conditions
 277 where the causal structure was present (i.e., the Technical and Causal Reasoning conditions),
 278 cumulative improvement progressively became more challenging in Experiment 2 compared to
 279 Experiment 1 (Supplementary Figures 2 and 3).

280 While patterns of cumulative improvement did not differ between the Technical and Causal
 281 Reasoning conditions in either experiment (Figures 2 and 4), our results indicate that exposure to
 282 the physical version of the task influenced how naïve learners explored the parameter space. In
 283 Experiment 1, first-generation participants frequently produced balanced configurations across all
 284 conditions (Figure 5.a). However, while balanced configurations dominated in both the Causal
 285 Reasoning and Pure Cultural Transmission conditions, participants in the Technical Reasoning

286 condition generated more unbalanced configurations with their centroid (i.e., their centre of mass)
 287 in the top-right quadrant. A similar pattern emerges in Experiment 2: balanced configurations were
 288 again the most frequent in both abstract conditions, whereas participants in the Technical
 289 Reasoning condition tended to produce unbalanced configurations with their centre of mass in the
 290 top-left quadrant (Figure 5.b). These findings indicate that awareness of the task's mechanical
 291 nature influenced participants, biasing initial exploration toward more accelerating wheels in
 292 Experiment 1 and more decelerating wheels in Experiment 2.

293 Two findings help explain why the biased exploration observed in the Technical Reasoning
 294 condition did not result in faster cumulative improvement compared to the Causal Reasoning
 295 condition. First, contrary to our predictions, facing the physical task did not reduce the extent of
 296 exploration compared to the abstract task. In fact, exploration was broader in the Technical
 297 Reasoning condition in both experiments, even when considering physical properties directly
 298 relevant to the wheel's dynamics, such as the centre of mass and inertia (Supplementary Figures
 299 4 and 5). This indicates that while exploration in the Technical Reasoning condition is influenced
 300 by physical cues, participants still vary their configurations substantially, reflecting the vagueness
 301 and partial nature of their underlying causal model. Second, our results show that participants do
 302 not need physical cues to effectively leverage the task's causal structure. Even when presented
 303 with the task in its abstract form, participants were able to converge on promising regions of the
 304 parameter space: unbalanced configurations with their centroid in the top-right quadrant in
 305 Experiment 1 and in the top-left quadrant in Experiment 2 (Figure 5c-d).

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 308 **Figure 5.** Initial versus final exploration patterns across conditions in Experiments 1 and 2. Radial plots show
 309 the number of configurations whose centroid falls within each quadrant of the wheel (upper-right, bottom-right,
 310 bottom-left, and upper-left). The dotted circle indicates the number of configurations with weights/sliders
 311 positioned at equal distances from the axis (i.e. balanced configurations). Top row: Panels A and B depict the
 312 first trial of first-generation participants (i.e., Trial 1) in Experiments 1 and 2, respectively. Participants in the
 313 Technical Reasoning condition appropriately biased their initial exploration toward unbalanced configurations,
 314 favoring accelerating wheels in Experiment 1 (with a centre of mass in the upper right quadrant due to their

315 *top and right weights being positioned farther from the axis than their bottom and left weights) and decelerating*
316 *wheels in Experiment 2 (with a centre of mass in the upper left quadrant due to their top and left weights being*
317 *positioned farther from the axis than their bottom and right weights). In contrast, balanced configurations*
318 *dominated the early exploration in both the Causal Reasoning and Pure Cultural Transmission conditions.*
319 *Bottom row: Panels C and D depict the last trial of fifth-generation participants (i.e., Trial 25) in Experiments*
320 *1 and 2, respectively. By the end of the experiment, participants in the Causal Reasoning condition had*
321 *converged toward exploration patterns similar to those observed in the Technical Reasoning condition.*
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324 **Discussion**

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326 Our study set out to examine the role of reasoning abilities in technological improvement.
327 Unlike previous experiments that tested whether performance gains across generations were
328 correlated with increased understanding [17, 20], we introduced a novel methodology that allowed
329 us to experimentally manipulate participants' ability to rely on either causal or technical reasoning
330 while solving a task, enabling a rigorous evaluation of their contribution to technological
331 improvement.

332 In our baseline, Pure Cultural Transmission condition, the causal structure was absent,
333 preventing participants from correctly predicting which configurations may yield above-average
334 performance. As a result, between-generation improvement could only occur through the retention
335 of modifications that happened to outperform inherited solutions by chance. Despite this,
336 improvement across generations was observed in both experiments, confirming that causal
337 reasoning is not necessary for cultural improvement to occur [7, 17, 18].

338 This Pure Cultural Transmission condition provides a baseline against which to compare
339 the pace of cultural improvement when participants can rely on causal reasoning to exploit patterns
340 of covariation between input and output variables. Our results reveal that the presence of a causal
341 structure enables participants to effectively detect performance gradients and preferentially explore
342 promising regions of the parameter space. This is reflected in end-of-experiment exploration
343 patterns, which were biased toward upper-right-offset configurations in Experiment 1 and upper-
344 left-offset configurations in Experiment 2. These results demonstrate that causal reasoning can
345 promote the emergence of beneficial modifications, thereby accelerating the pace of cultural
346 evolution [5, 23].

347 Yet, our results reveal that the benefits of causal reasoning vary significantly depending on
348 the circumstances. This is particularly evident in Experiment 2, where the presence of a causal
349 structure is highly beneficial during the early stages of cultural evolution but less so in later stages.
350 This contrasts with Experiment 1, where the benefits of a causal structure are maintained during
351 the later stages of the experiment. This difference stems from the distinct payoff structures used in
352 Experiments 1 and 2. In both experiments, causal reasoning helped participants bias their
353 exploration toward regions of the parameter space where the highest-rewarding solutions lie. In
354 Experiment 1, these regions also happen to be safe, with non-viable configurations being
355 uncommon (Figure 3.a). In contrast, in Experiment 2, an exploration bias toward high-reward areas
356 inadvertently led participants into riskier regions of the parameter space, where non-viable

357 configurations are more frequent (Figure 3.b). This difference in payoff structure between
358 Experiments 1 and 2 reveals the limitations of causal reasoning in driving cultural improvement.
359 When learners are initially uncertain about what constitutes a good solution, even partial causal
360 models can be helpful because they allow individuals to exploit the most salient performance
361 gradients and accelerate the discovery of beneficial modifications. However, as solutions improve
362 and the room for further improvements narrows, these partial models become less useful.

363 These findings align with the view that individuals encode causal patterns in a highly sparse
364 manner [24], such that their causal models lack the detailed mechanistic structure needed to
365 support fine-grained predictions about the effects of specific changes [25]. Taken together, our
366 results help reconcile opposing views about the role of causal reasoning in cultural evolution. On
367 one hand, they demonstrate the contribution of causal reasoning to technological improvement; on
368 the other, they underscore its limitations [17, 26]. Most notably, our experiments reveal how causal
369 reasoning becomes relatively ineffective as learners approach the 'barrier' to artifact improvement
370 [10] (see also [27]). Once this barrier is reached, attempts to improve would often lead to worse
371 outcomes, as shown by the early performance of late-generation participants, who frequently
372 produced solutions less efficient than those they had inherited (Figure 4, see also [17]). This means
373 that further improvement would largely depend on cultural evolutionary processes in which chance
374 modifications are selectively retained [15], a process whose effectiveness depends heavily on
375 factors such as group size and connectedness [15, 28, 29]. This helps explain why between-
376 generation improvement was sometimes modest or absent in our experiments, as typical one-
377 person-per-generation transmission chains provide limited opportunities for cultural evolutionary
378 processes to operate. In our setup, participants inherited only two configurations from a single
379 cultural demonstrator, and the continuation of the cumulative process depended entirely on one
380 individual per generation. In more realistic conditions, multiple learners help buffer against the risk
381 of cultural loss, and the presence of more individuals increases the likelihood that beneficial
382 modifications will arise [13, 15, 30-32].

383 A striking finding of our study is the lack of benefits from being aware of the task's
384 mechanical nature and observing the wheel's motion compared to the abstract condition. This
385 indicates that the causal models formed in the Technical Reasoning condition were not more fine-
386 grained and remained similarly limited in their ability to predict the payoff of untested configurations.
387 The fact that participants did not require physical cues to leverage the task's causal structure raises
388 the question of whether causal models about physical phenomena depend on a content-specific
389 form of reasoning or instead rely on more domain-general reasoning abilities [33, 34].

390 Yet, it is noteworthy that awareness of the task's mechanical nature influenced exploration
391 among naïve participants, even though they had not previously interacted with our experimental
392 apparatus. Participants biased their initial exploration in meaningful ways, likely drawing on prior
393 experience with analogous systems and transferring relevant, albeit imprecise, causal models to a

394 novel task. This highlights the potential role of analogical reasoning in cultural evolution [35]. The
395 benefits of this form of reasoning may have been limited in our setup because the task involved
396 optimizing an existing solution (i.e., improving toward a fixed optimum). While this is a critical
397 component of cumulative cultural evolution, it may not fully capture the challenges associated with
398 open-ended cumulative cultural evolution, through which increasingly complex and ever more
399 efficient solutions can emerge [36-40]. For instance, open-ended evolutionary dynamics may
400 depend on specific types of modifications not captured by our experimental task, such as cultural
401 exaptation (in which a solution originally developed for one purpose is repurposed in a new context
402 [8, 37]) and combinatorial innovation (where elements from different domains are combined to
403 generate novel and more effective solutions [27, 41, 42]). Future work should extend our
404 methodology to tasks that not only involve improving existing technologies but also creating new
405 ones, an activity that may demand reasoning abilities beyond those required for marginal
406 improvement alone [36, 38].

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Materials and Methods

411 **Ethics Statement.** All methods were approved by the Toulouse School of Economics Review
412 Board for Ethical Standards in Research (11-23-16). All participants provided informed consent
413 before taking part in the experiment.

414 **Participants.** Two experiments were conducted with a total of 900 participants (450 women), all
415 recruited via the online platform Prolific. The subjects ranged in age from 18–51 years (mean =
416 28.7 years; s.d. = 4.8 years).

417 **Experimental conditions.** All participants were randomly assigned to one of three experimental
418 conditions. In all conditions, participants completed an optimization task involving four
419 weights/sliders that could be positioned at one of 12 discrete locations, creating a parameter space
420 of 20,736 unique configurations. Each participant completed five trials with the goal of maximizing
421 their cumulative payoff and received feedback after each trial. In the Technical Reasoning
422 condition, participants completed a computerized version of the wheel task used in Derex et al.
423 (2021), which accurately simulated the physics of the original task (Supplementary Figures 6 and
424 7). In each trial, participants set the position of four weights, which determined the wheel's motion
425 upon release (see 'Task versions' below for details about the physics of the wheel). After validating
426 their configuration, they observed the wheel's motion and received feedback in the form of a payoff
427 once the wheel reached the end of the rails (or once the simulation stopped for wheels that failed
428 to descend). In the Causal Reasoning and Pure Cultural Transmission conditions, participants set
429 the position of four sliders arranged like the spokes of the wheel (Figure 1). After validating their
430 configuration, they received feedback in the form of a payoff. In the Causal Reasoning condition,

431 the configuration-payoff mapping was identical to that in the Technical Reasoning condition,
432 meaning that the same configuration produced the same payoff in both conditions. In the Pure
433 Cultural Transmission condition, the configuration-payoff mapping was randomized, so that each
434 configuration was mapped to a payoff outcome from the Technical Reasoning condition. These
435 mappings were randomized between chains, but remained consistent within a given chain.
436 Screenshots showing what participants saw in each condition are publicly available at
437 <https://www.github.com/aseyq/causal-reasoning>.

438 **Experimental design.** In each condition, participants were placed into one of 30 independent
439 transmission chains, each consisting of five individuals. No statistical methods were used to pre-
440 determine sample sizes; however, the number of independent chains in our study was more than
441 twice that reported in previous publications [17, 20]. Each participant completed five trials and
442 could, before each trial, consult the two most recent configurations produced within their chain
443 along with their associated payoffs. . After three trials, participants were reminded that their last
444 two configurations would be transmitted to the next participant in the chain. Participants earned
445 between 0 and 0.4 pounds per trial, depending on the performance of their configuration. All
446 participants, except those in the first generation, received social information in the form of the last
447 two configurations and associated payoffs of the preceding participant in their chain.

448 **Task versions.** In Experiment 1, the wheel's weights were of equal visual dimensions, indicating
449 equal mass, as in the original physical task [17]. The goal for participants in the Technical
450 Reasoning condition was to minimize the time it took for the wheel to descend a simulated 0.92 m
451 inclined track. In Experiment 2, the wheel featured weights of unequal visual dimensions, indicating
452 unequal mass, with the right-side weight having a simulated mass twice as heavy as the other three
453 weights (Supplementary Figure 1). The goal was inverted, requiring participants to maximize the
454 descent time over a 0.33 m inclined track. In both task versions, the dynamics of the wheel
455 depended on two variables: its moment of inertia and the position of its centre of mass. The wheel's
456 moment of inertia is determined by how mass is distributed relative to its axis of rotation. Wheels
457 with a smaller moment of inertia (i.e., weights positioned closer to the axis) require less torque to
458 increase angular momentum and spin faster. Additionally, the position of the centre of mass affects
459 the wheel's initial acceleration. When the centre of mass is located in the wheel's upper-right
460 quadrant (assuming the wheel descends from left to right), more potential energy is converted into
461 angular kinetic energy, resulting in greater increases in angular momentum. In Experiment 1,
462 wheels featured equal weights, meaning that unbalanced configurations had their centre of mass
463 positioned away from the axis of rotation. In Experiment 2, wheels had unequal weights, so that
464 balanced configurations systematically had their centre of mass positioned away from the axis of
465 rotation. Configurations that resulted in a non-rolling wheel (due to the position of its centre of mass)
466 received a performance score of zero in both task versions. Across treatments and conditions, the

467 maximum payoff per trial was 0.4 pounds. Sliders in the abstract experimental conditions had the
468 same visual dimensions as those in the Technical Reasoning condition in both task versions.

469 **Procedure.** After indicating their interest in the study and providing initial consent on Prolific,
470 participants connected to the experimental interface. They were then presented with the study's
471 consent form and could proceed with the experiment if they approved. Participants were randomly
472 assigned to one experimental condition and one sex-segregated transmission chain. On-screen
473 instructions followed. In the abstract conditions, participants were informed that they were tasked
474 with "optimizing a configuration by setting the position of four movable sliders." In the Technical
475 Reasoning condition, they were told to "optimize a wheel traveling down an inclined rail by setting
476 the position of four movable weights." Regardless of the condition, participants were informed that
477 there was a relationship between the configuration and the reward they would earn and that
478 repeating the same configuration would result in the same payoff. Participants were also informed
479 that they were part of a chain and that the task was collective. They were told they would complete
480 five trials and that their last two configurations would be transmitted to the next participant in the
481 chain, and were informed of their position in the transmission chain. Participants were further
482 notified that their final earnings would depend on both their own cumulative payoff and the payoff
483 of the next participant in the chain. They were not informed of the payoff associated with the best
484 possible configuration. Participants had to answer two comprehension questions and could not
485 proceed if they provided incorrect answers twice.

486 **Analyses.** We used Bayesian multilevel models fitted in R [43] using the *rethinking* package [44].
487 Results are reported as posterior means with 95% credible intervals. Codes used to analyse the
488 data are publicly available at <https://www.github.com/aseyq/causal-reasoning>. Full model outputs
489 are provided in the Supplementary Information section. No data points were excluded from the
490 analyses.

491 *Payoff across generations.* To assess whether payoff improved across generations within a given
492 experimental condition, we fitted a linear model with 'Payoff' as the outcome variable, 'Generation'
493 as the predictor variable, and 'Participant Identity' and 'Chain Identity' as random effects. To
494 determine whether payoff was higher or improved more rapidly across generations in one condition
495 compared to another, we fitted a linear model with 'Payoff' as the outcome variable, 'Generation,'
496 'Condition,' and the interaction term 'Generation: Condition' as predictor variables, with 'Participant
497 Identity' and 'Chain Identity' as random effects. In both types of analyses, the dataset included all
498 participants' five trials and all five generations.

499 *Exploration.* To assess whether facing the physical task reduced exploration compared to the
500 abstract task, we calculated four-dimensional Euclidean distances between each configuration
501 produced by first-generation participants and the average configuration of that condition. We then

502 tested whether these distances differed between the Technical and Causal Reasoning conditions
503 by fitting a linear model with 'Distance' as the outcome variable, 'Condition' as the predictor
504 variable, and 'Participant Identity' as a random effect. Similar models were run to assess
505 exploration in terms of the position of the centroid of the configurations (i.e., the center of mass of
506 the wheel in Experiment 1) and their compactness (i.e., the inertia of the wheel in Experiment 1).
507 For the former analyses, we calculated two-dimensional Euclidean distances based on the centroid
508 coordinates, determined by subtracting the position of the left slider/weight from that of the right
509 slider/weight and the position of the bottom slider/weight from that of the top slider/weight. For
510 analyses of compactness, we calculated one-dimensional Euclidean distances based on
511 compactness level, determined by summing the positions of the four sliders/weights. In these
512 analyses, only data from first-generation participants were included to ensure that exploration
513 patterns reflected participants' intuitive search strategies rather than being influenced by
514 information inherited from previous participants. In Figure 5, configurations were considered
515 balanced when the coordinates of the centroid (x , y) both equaled zero. The centroid was classified
516 as falling within the upper-right quadrant when $x \geq 0$ and $y \geq 0$, the bottom-right quadrant when $x \geq$
517 0 and $y < 0$, the bottom-left quadrant when $x \leq 0$ and $y < 0$, and the upper-left quadrant when $x \leq 0$
518 and $y \geq 0$.

519 *Deviation from the pre-registered analyses.* Compared to the pre-registered analyses, the models
520 investigating 'Payoff' across generations do not include 'Trial' or the interaction term
521 'Trial:Condition' as predictor variables. Under the original model specification, the model had
522 difficulty allocating variance between the 'Trial' and 'Generation' predictors, leading to misleading
523 parameter estimates for both main effects and interaction terms. To address this issue and align
524 the analyses more closely with our primary focus on 'Generation', we removed the 'Trial' variable
525 from all models.

526 **Pre-registration.** Both experiments were pre-registered on AsPredicted prior to data collection.
527 Experiment 1 was pre-registered under ID #169017 (Technical and Causal Reasoning conditions)
528 and ID #173,042 (Pure Cultural Transmission condition), and Experiment 2 under ID #212,783.
529 Each pre-registration specified the experimental design, hypotheses, sample size, exclusion
530 criteria, and planned analyses.

531 **Data and Code Availability.** The data and scripts for the analyses are publicly available at:
532 <https://www.github.com/aseyq/causal-reasoning>.

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